# Contributions from the DISC to **S** accomplish the Aeolus mission objectives

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#### Knowledge for Tomorrow

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**DISC** 

#### The Aeolus Data Innovation and Science Cluster DISC

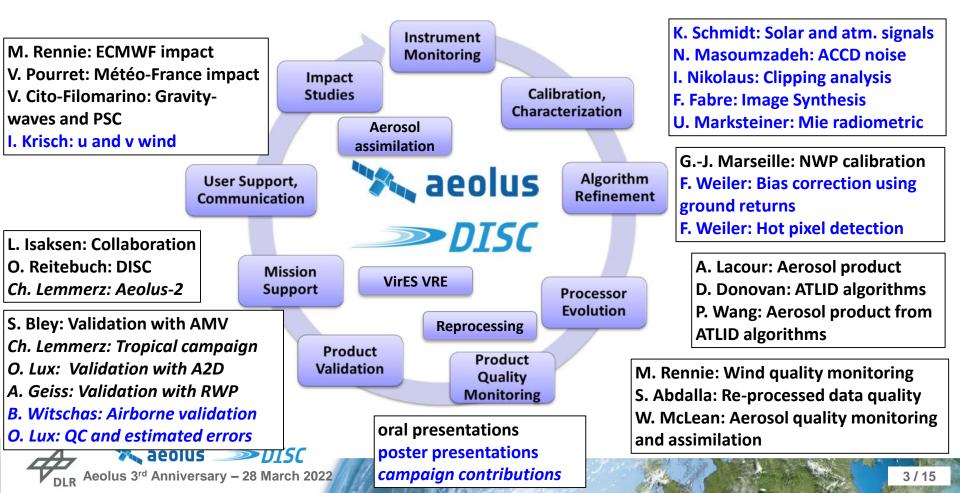
- DISC established in 2019 from teams cooperating since 2003 on Aeolus algorithms, processors, impact experiments, campaigns
- 14 international partners with about 40 scientists and engineers coordinated by DLR
- Broad range of experts for laser, lidar, retrieval algorithms, software development, calibration, validation, and NWP monitoring and impact assessment cover all aspects of Aeolus
- DISC funded by ESA with strong links to all ESA entities (ESTEC, ESRIN, ESOC) and space industry (Airbus, Leonardo)





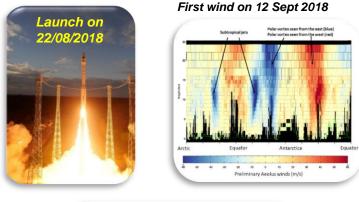


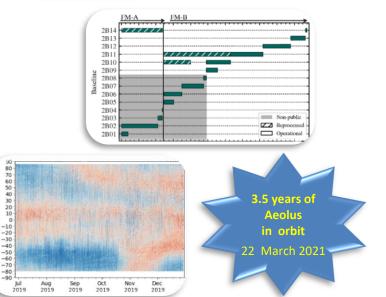
#### Aeolus DISC Tasks and Contributions to this Workshop



#### **Outline of the talk**

- Aeolus/DISC highlights since launch
- Baselines and reprocessing
- ALADIN performance
  - Signal evolution and random errors
  - Sources of bias and corrections
- Summary and Conclusion

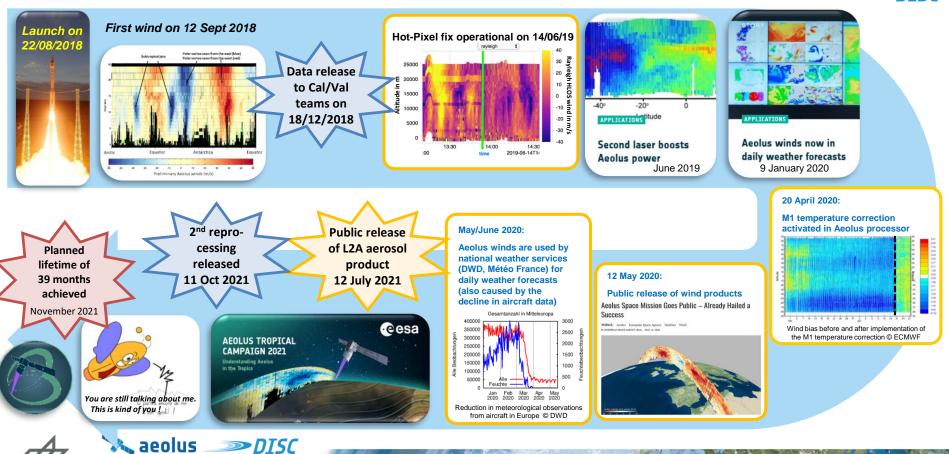




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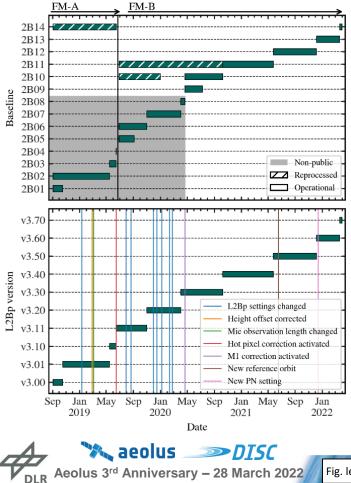
## Aeolus and DISC highlights during first 3.5 years in orbit

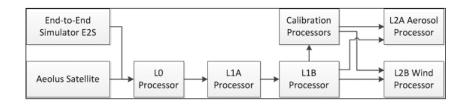


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#### Frequent update of operational processors by DISC

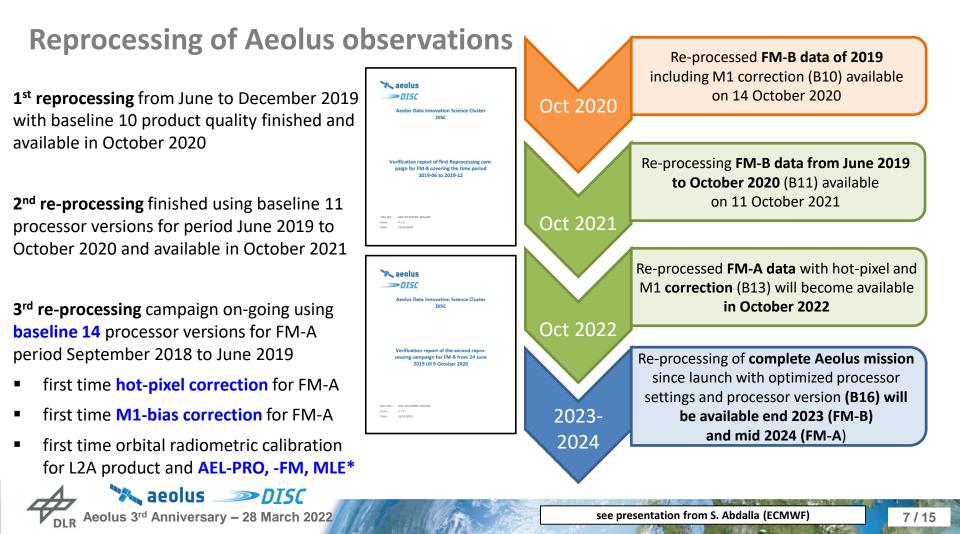




- success of Aeolus as an Earth Explorer mission is its operational assimilation of wind product by several NWP centers
- near-real time data production by ESA-PDGS and frequent update of full chain of operational processors
- major operational processor deliveries from DISC to ESA-PDGS every 6 months, which results in new product quality and product content - called baselines
- update to baseline B14 planned for March 29, 2022

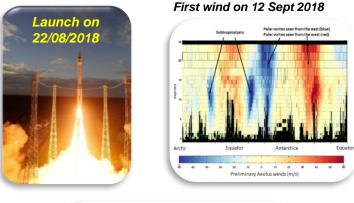
E2S, L0/L1A/L1B and L2A operational processor by **D. Huber (DoRIT)** L2B operational processor by **J. de Kloe (KNMI)** calibration processors at ACMF and codadef by **S&T and ABB** processor handover and anomaly management by **Serco** 

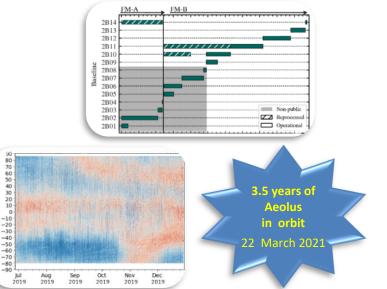
Fig. left by A. Geiß (LMU)



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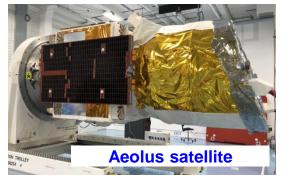


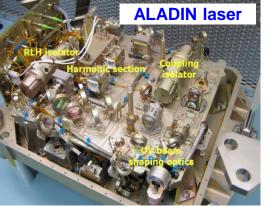


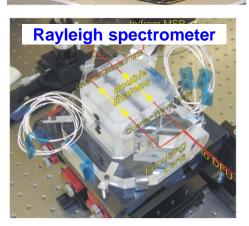
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-90

#### ALADIN – the first wind lidar in space







A2D optical receiver

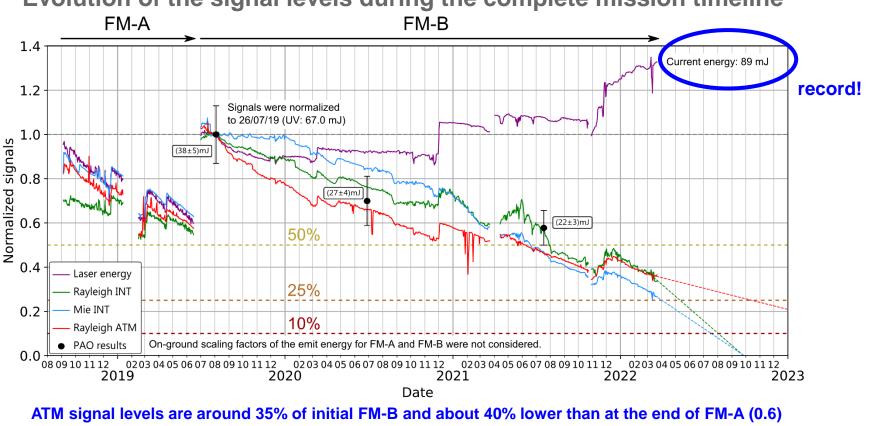
- **First European lida**r in space after 20 years of development challenges
- First wind lidar and first HSRL in space - worldwide unique mission
- **Highest power-aperture** product for a lidar in space (40 mJ - 85 mJ /  $\emptyset$  1.5 m)
- First high-power, ultraviolet (UV) laser in space (@ 354.8 nm) with stringent requirements on frequency stability
- **Doppler wind lidar** principle straightforward but incredibly small effect

Doppler Equation:  $\Delta f = 2 f_0 \frac{\mathbf{V}_{LOS}}{c}$ 

relative Doppler shift  $\Delta f/f_0 \approx 10^{-8}$ 1 m/s (LOS)⇔ 5.64 MHz ⇔ 2.37 fm size H-atom 50 pm, H-nucleus 1.2 fm



Reitebuch et al. (2009), JAOT; Reitebuch (2012), Springer; Reitebuch/Hardesty (2022), Springer



## Evolution of the signal levels during the complete mission timeline

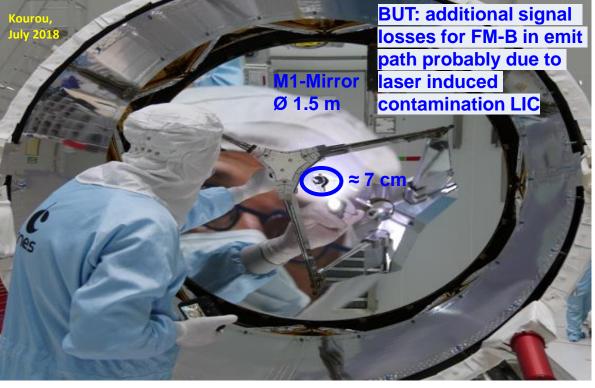
=> extrapolation to 25% (ATM) by October 2022 and to 10% (INT, ATM) by August 2022

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Figure by O. Lux (DLR), see poster by K. Schmidt (DLR) on Rayleigh and U. Marksteiner (DLR) on Mie

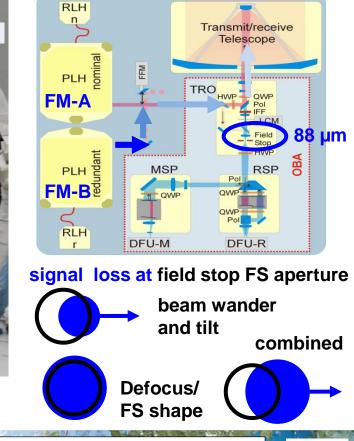
#### What causes the signal loss for ALADIN?

# N? FOV 18 μrad 7 m @ 400 km



from Aeolus blog https://aeolusweb.wordpress.com/





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#### What influences the wind random error?

- 1. Laser emit energy and optical signal transmission in laser emission and receive path for atmospheric signal
- 2. Solar background noise mainly for Rayleigh winds
  - ⇒ Impact higher than expected due to lower atmospheric signal
  - Seasonal variation of solar background by factor 18: Rayleigh random errors increased from 7-8 m/s to >15 m/s in summer months for polar regions and stratosphere

solar background Rayleigh data age (average over 465 observations) runnins 28 km 28-14.01.2019 M-A switch off 16.06.201 witch from FM-A to FM-B  $1.2 \times 10$ 22.03.202 switch to survival mode Rayleigh solar background useful signals [ACCD counts] 13.04.202  $I F \Delta$ 22.10.202 switch to survival mode  $1.0 \times 10$ L2B wind 8,0×10 random error for 1 orbit 6,0×10 on Nov 11, 2021  $4,0 \times 10$ -15.4 12.5 40.5 Lat: -69.9 -43.2 68.2 82.0 55.2 27.4 -0.7 -28.6 -56.0 -79.8  $2,0 \times 10$ -96.1 -102.7 -108.3 -113.7 -123.8 101.1 70.9 63.5 58.4 52.7 43.0 -5.3 -106.0 L2B HLOS wind error estimate (m/s) (missing values=-1) Mean=9.08 Std.dev.=19.30 Count=10324 16.50 06-05-2021 18-11-2018 17-05-2019 13-11-2019 11-05-2020 07-11-2020 02-11-2021 01-05-2022 20 m/s 6 m/s Aeolus 3<sup>rd</sup> Anniversary – 28 March 2022 Figures by K. Schmidt (DLR) and M. Rennie (ECMWF), see also poster by K. Schmidt 12/15 

Orbital variation of Rayleigh solar background noise

6×10<sup>5</sup>

[structure] 4×10

5 2×10

IX10

03-01 00:00:00

ayleigh 3×10 March 1, 2019

03-01 02:24:00

03-01 04:48:00

date and time in 2019 (MM-DD HH:MM:SS)

03-01 07:12:00

#### Aeolus bias and corrections 1/2

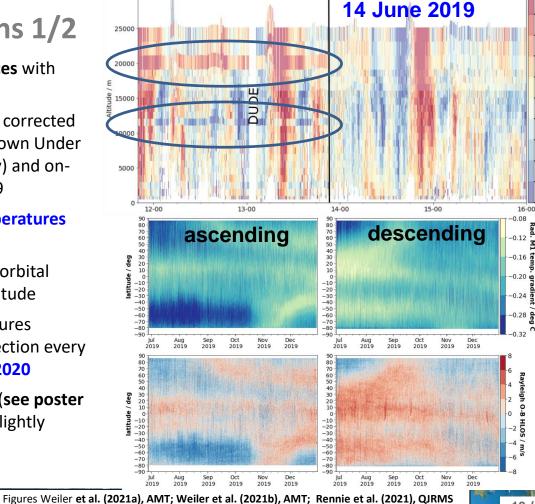
**combination of several unexpected error sources** with different temporal characteristics:

- higher dark current rates for "hot pixels"=> corrected with special instrument operation DUDE (Down Under Dark Experiment, 4 per day, today 8 per day) and onground correction in L1B since 14 June 2019
- 2. variations of the **M1 telescope mirror temperatures** (mean and gradient along mirror)
  - ⇒ Rayleigh and Mie bias as a function of orbital phase (argument of latitude) and longitude
  - ⇒ use correlation between M1 temperatures and ECMWF model bias (O-B) for correction every 12/24 h; implemented since 20 April 2020
  - ⇒ on-going study to use ground-returns (see poster
     F. Weiler): NWP model independent, slightly
     lower performance of 10%

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details on ACCD noise (poster N. Masoumzadeh) and HP detection (F. Weiler)

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30000

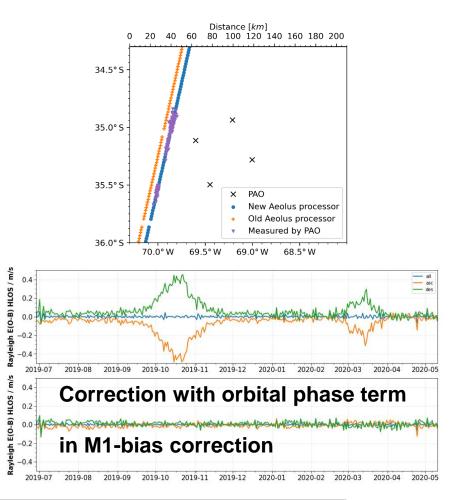
#### Aeolus bias and corrections 2/2

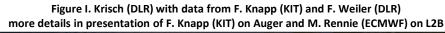
#### Other unexpected error sources

- Error in the on-board software in calculation of residual projection of the satellite ground speed on the line-ofsight => corrected with L1b V7.09.1 (baseline B11 from 8 October 2020)
- Slow drifts in the illumination of the Rayleigh/Mie spectrometers causing a slowly drifting constant bias => corrected with M1-bias correction
- Geolocation error for longitude by 0.075° (≈ 8 km at equator) discovered with help of Auger observatory; is corrected in L1B V7.12 (baseline 14)
- 6. Enhanced bias of up to 0.4 m/s in October and March due to Aeolus orbit on terminator with permanent twilight => harmonic orbital variation of bias; is corrected as part of M1-bias correction for B14

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#### **Summary and Conclusion**

- First European lidar and first wind lidar in space in operation for 3.5 years: lifetime objective was achieved.
- Mission objective to demonstrate wind lidar technology including operation of a laser in the ultraviolet spectral region was achieved.
- Mission objective to demonstrate positive impact for numerical weather prediction was achieved: ECMWF, DWD, Météo-France, UK Met Office and NCMRWF are using Aeolus wind products in operation and show positive impact; positive impact is demonstrated in various other global models, e.g. ECCC, NOAA.
- Aeolus demonstrates the high-spectral resolution lidar approach for retrieval of aerosol optical properties for the first time in orbit
- Aeolus DISC contributions were key to achieve mission objectives.
- Aeolus paves the way for the future lidars from Europe (EarthCARE and Merlin) and a European operational follow-on wind lidar mission in 2030+.
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